

Hamilton-Jacobi equation and non-holonomic dynamics

Why use algebroid theory to describe the H-J equation?

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Focus Program on Geometry, Mechanics and Dynamics
and the Legacy of Jerry Marsden

Advances about a formalism which allows to describe Hamilton-Jacobi equation for a great variety of mechanical systems

- Unconstrained systems (Classical hamiltonian systems, reduced hamiltonian systems,.....)
- nonholonomic systems subjected to linear or affine constraints
- dissipative systems subjected to external forces
- time-dependent mechanical systems
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D Iglesias, M de León, D Martín de Diego (2008)

T Ohsawa, A Bloch (2009)

M de León, JC Marrero, D Martín de Diego (2010)

J F Carinena, X Gracia, G Marmo, E Martínez, M C Muñoz-Lecanda, N Román-Roy (2010)

P Balseiro, JC Marrero, D Martín de Diego, E P (2010)

M Leok, T Ohsawa, D Sosa (2011)

INGREDIENTS

- Q configuration space (manifold) (q^i)
- $\tau_Q^* : T^*Q \rightarrow Q$ phase space of momenta (q^i, p_i)
- $H : T^*Q \rightarrow \mathbb{R}$ Hamiltonian function $H(q^i, p_i)$

↓

$X_H \in \mathfrak{X}(T^*Q)$ hamiltonian vector field $X_H = \frac{\partial H}{\partial p_i} \frac{\partial}{\partial q^i} - \frac{\partial H}{\partial q^i} \frac{\partial}{\partial p_i}$

- $W : Q \rightarrow \mathbb{R}$ the characteristic function $W(q^i)$

Classical Hamilton-Jacobi Theorem

The following sentences are equivalent

- 1 For every $c : I \rightarrow Q$, $c(t) = (q^i(t))$ integral curve of

$$X_H^W = T\tau_Q^* \circ X_H \circ dW \in \mathfrak{X}(Q) \quad \frac{dq^i}{dt} = \frac{\partial H}{\partial p_i}(q(t), \frac{\partial W}{\partial q^i}(q(t)))$$

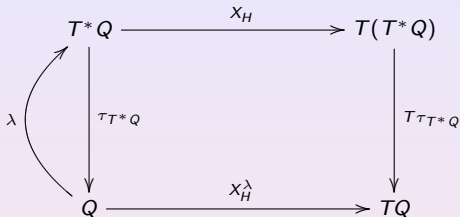
↓

$dW \circ c : I \rightarrow T^*Q$ is an integral curve of X_H

- 2 W satisfies **Hamilton-Jacobi equation**

$$H \circ dW = \text{constant}, \quad H(q^i, \frac{\partial W}{\partial q^i}) = \text{constant}$$

Let $\lambda \in \Omega^1(Q)$ be a closed 1-form ($d\lambda = 0$)



Theorem

$c : I \rightarrow Q$ integral curve of $X_H^\lambda \Rightarrow \lambda \circ c$ integral curve of X_H ,

\Leftrightarrow

X_H and X_H^λ are λ -related (i.e. $T\lambda(X_H^\lambda) = X_H$).

\Leftrightarrow

$d(H \circ \lambda) = 0$ **Hamilton-Jacobi equation**

TOOLS

$TQ \xrightarrow{\tau_{TQ}} Q \rightsquigarrow$ vector bundle $\tau_D : D \rightarrow Q$ over a manifold Q

The canonical symplectic 2-form ω_Q in $T^*Q \simeq$ The canonical Poisson bracket $\{\cdot, \cdot\}_{T^*Q}$ on $T^*Q \rightsquigarrow$ a linear Poisson bracket $\{\cdot, \cdot\}_{D^*}$ on D^*

A Hamiltonian function $H : T^*Q \rightarrow \mathbb{R} \rightsquigarrow$ a function $H : D^* \rightarrow \mathbb{R}$

A section $\lambda : Q \rightarrow T^*Q$ such that $d\lambda = 0 \rightsquigarrow$ a section $\lambda \in \Gamma(D^*)$ which is closed with respect to a *certain differential*

INGREDIENTS

- Q manifold (configuration space)
- D a distribution on Q (constraint distribution)
- g a Riemannian metric on Q
- $V : Q \rightarrow \mathbb{R}$ a real function on Q (Potential)

 \Downarrow

$$L : TQ \rightarrow \mathbb{R}, \quad L(v) = \frac{1}{2}g(v, v) - V(\tau(v))$$

 $\mathbb{F}L : TQ \rightarrow T^*Q$ Legendre transformation

 $\mathbb{F}L \equiv$ The vector bundle isomorphism induced by the metric g
 \Downarrow
 $\bar{D} = \mathbb{F}L(D)$ the constraint Hamiltonian subbundle of T^*Q

- $H : T^*Q \rightarrow \mathbb{R}$ Hamiltonian function

 \Downarrow

$$\bar{X}_H \in \mathfrak{X}(D^*) \quad \bar{X}_H = Ti_D^* \circ X_H \circ P^*$$

$$TQ = D \oplus D^\perp \quad P : TQ \rightarrow D, \quad P^* : D^* \rightarrow T^*Q$$

$$i_D : D \rightarrow TQ, \quad i_D^* : T^*Q \rightarrow D^* \quad Ti_D^* : T(T^*Q) \rightarrow TD^*$$

$\mathcal{I}(D^0) \equiv$ the algebraic ideal generated by D^0

Hamilton-Jacobi Theorem for nonholonomic systems

Let $\lambda \in \Omega^1(Q)$ taking values into \bar{D} and satisfying $d\lambda \in \mathcal{I}(D^0)$. Then the following conditions are equivalent:

- 1 For every integral curve $c : \mathbb{R} \rightarrow Q$ of

$$X_H^\lambda = (T\pi_Q) \circ X_H \circ \lambda \in \mathfrak{X}(Q)$$

then $\lambda \circ c$ is an integral curve of \bar{X}_H .

- 2 $d(H \circ \lambda)(Q) \subset D^0$

D. IGLESIAS, M. DE LEÓN, D. MARTÍN DE DIEGO 2008

TOOLS

$D \xrightarrow{\tau_D} Q \rightsquigarrow \tau_D : D \rightarrow Q$ vector bundle over a manifold Q

The nonholonomic bracket on D^* \rightsquigarrow an almost linear Poisson $\{\cdot, \cdot\}_{D^*}$ bracket of functions on D^* , i.e., in general, does not satisfy Jacobi identity

$$\{F, G\}_{D^*} = \{F \circ i_D^*, G \circ i_D^*\} \circ P^*, \quad F, G \in C^\infty(D^*)$$

$$TQ = D \oplus D^\perp \quad P : TQ \rightarrow D, \quad P^* : D^* \rightarrow T^*Q$$

$$i_D : D \rightarrow TQ, \quad i_D^* : T^*Q \rightarrow D^*$$

A Hamiltonian function $H : T^*Q \rightarrow \mathbb{R} \Rightarrow \mathcal{H} = H \circ P^* : D^* \rightarrow \mathbb{R} \rightsquigarrow$ function $\mathcal{H} : D^* \rightarrow \mathbb{R}$

\Downarrow

$$\bar{X}_H \in \mathfrak{X}(D^*) \quad \bar{X}_H(F) = X_{\mathcal{H}}(F) = \{F, \mathcal{H}\}_{D^*}$$

A section $\lambda : Q \rightarrow T^*Q$ taking values on \bar{D} such that $d\lambda(Q) \subset \mathcal{I}(D^0) \rightsquigarrow$ A section $\lambda \in \Gamma(D^*)$ and is it closed with respect to a *certain differential operator?*

INGREDIENTS:

- $\tau_D : D \longrightarrow Q$ a vector bundle



$\tau_{D^*} : D^* \longrightarrow Q$ its dual vector bundle

- A linear almost Poisson bracket ¹ $\{\cdot, \cdot\}_{D^*}$ on D^*



$d^D : \Gamma(\wedge^k D^*) \rightarrow \Gamma(\wedge^{k+1} D^*)$ differential operator

¹linear means that the bracket of two linear functions is a linear function

$\tau_D : D \rightarrow Q$ vector bundle with linear almost Poisson bracket $\{\cdot, \cdot\}_{D^*}$ on $D^* \rightarrow Q$

$$\{\hat{X} : D^* \rightarrow \mathbb{R}/\hat{X} \text{ is linear}\} \iff \Gamma(D) = \{X : Q \rightarrow D/X \text{ is a section of } \tau\}$$

What is the corresponding structure on D ?



The bracket of two linear functions with respect to $D^* \rightarrow Q$ is again linear

The bracket on the space of sections of D

$$[[\cdot, \cdot]]_D : \Gamma(D) \times \Gamma(D) \rightarrow \Gamma(D) \text{ skew-symmetric}$$

$$\widehat{[[X, Y]]_D} = -\{\hat{X}, \hat{Y}\}_{D^*}$$

The bracket of a linear function and a basic function $f \circ \tau_{D^*}$ is a basic function

The vector bundle morphism between D and TQ

$$\rho_D : D \rightarrow TQ \text{ (anchor map)} \Rightarrow \rho_D : \Gamma(D) \rightarrow \mathfrak{X}(Q)$$

$$\rho_D(X)(f) \circ \tau_{D^*} = \{\hat{X}, f \circ \tau_{D^*}\}_{D^*}$$

$$[[X, fY]]_D = f[[X, Y]]_D + \rho_D(X)(f)Y, \quad \forall X, Y \in \Gamma(D), \quad \forall f \in C^\infty(Q)$$

$$\{ \{ \cdot, \cdot \}_{D^*} \text{ linear almost Poisson bracket on } D^* \}$$


$$\{ ([\cdot, \cdot]_D, \rho_D) \text{ skew-symmetric algebroid structure on } D \}$$

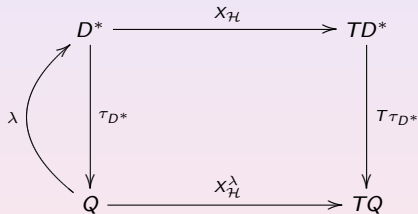
$$d^D : \Gamma(\Lambda^k D^*) \rightarrow \Gamma(\Lambda^{k+1} D^*)$$

$$d^D \Omega(\xi_0, \xi_1, \dots, \xi_k) = \sum_{i=0}^k (-1)^i \rho_D(\xi_i) (\Omega(\xi_0, \dots, \tilde{\xi}_i, \dots, \xi_k)) \\ + \sum_{i < j} \Omega([\xi_i, \xi_j]_D, \xi_0, \dots, \tilde{\xi}_i, \dots, \tilde{\xi}_j, \dots, \xi_k)$$

where $\xi_0, \xi_1, \dots, \xi_k \in \Gamma(D)$

$$(d^D)^2 \neq 0$$

- $\tau_D : D \rightarrow Q$ vector bundle
- $\{\cdot, \cdot\}_{D^*}$ linear almost Poisson bracket on D^*
- $\mathcal{H} : D^* \rightarrow \mathbb{R}$ Hamiltonian function $\Rightarrow X_{\mathcal{H}} = \{\cdot, \mathcal{H}\}_{D^*} \in \mathfrak{X}(D^*)$
- $\lambda : Q \rightarrow D^*$ be a section of $\tau_{D^*} : D^* \rightarrow Q$



$$X_{\mathcal{H}}^{\lambda} = T\tau_{D^*} \circ X_{\mathcal{H}} \circ \lambda$$

$W : Q \rightarrow \mathbb{R}$, $d^D W$ is not closed $d^D(d^D W) \neq 0$

- $\lambda \in \Gamma(D^*)$

$$\Upsilon^\lambda : \Omega^1(D^*) \rightarrow \Gamma(D), \quad \eta(\Upsilon^\lambda(\beta)) = \beta(\eta^\vee) \circ \lambda \quad \beta \in \Omega^1(D^*), \eta \in \Gamma(D^*)$$

$$\eta^\vee \in \mathfrak{X}(D^*)$$

$$\delta_{\mathcal{H}}^\lambda \in \Gamma(D) = \Upsilon^\lambda(d\mathcal{H})$$

Hamilton-Jacobi Theorem

$c : I \rightarrow Q$ integral curve of $X_{\mathcal{H}}^\lambda \in \mathfrak{X}(Q) \Rightarrow \lambda \circ c$ integral curve of $X_{\mathcal{H}} \in \Gamma(D^*)$

\Updownarrow

$$i_{\delta_{\mathcal{H}}^\lambda} d^D \lambda + d^D(\mathcal{H} \circ \lambda) = 0$$

M DE LEÓN, JC MARRERO, D MARTÍN DE DIEGO (2010)

The general distribution $\tilde{D} = \rho_D(D)$ *bracket generating*



$\{X_k, [X_k, X_l], [X_i, [X_k, X_l], \dots, X_j \in \tilde{D}\}$ spans $\mathfrak{X}(Q)$

$\text{Lie}^\infty(\tilde{D})$ the smallest Lie subalgebra of $\mathfrak{X}(Q)$ containing \tilde{D}

$$d^D(\mathcal{H} \circ \lambda) = 0$$



$\mathcal{H} \circ \lambda$ is constant on the leaves of the foliation $\text{Lie}^\infty(\tilde{D})$

- $\mathfrak{g} \rightarrow \{x\}$ with Lie-Poisson structure on \mathfrak{g}^* . Thus, if $D = \mathfrak{h}$ is a subspace of \mathfrak{g} , we obtain that the nonholonomic bracket (**nonholonomic Lie-Poisson bracket**)
- A principal G -bundle $\pi : Q \rightarrow Q/G$

$\tau_{TQ} : TQ \rightarrow Q$ is equivariant

\Downarrow

$TQ/G \rightarrow Q/G$

The linear Poisson structure on $(T^*Q)/G$ is characterized by the following condition: the canonical projection $T^*Q \rightarrow T^*Q/G$ is a Poisson epimorphism

the Hamilton-Poincaré bracket on T^*Q/G

D a G -invariant distribution on Q

\Downarrow

D/G is a vector subbundle of TQ/G

\Downarrow

the non-holonomic Hamilton-Poincaré bracket on D^*/G

INGREDIENTS

- $\pi : Q \rightarrow \mathbb{R}$ fibration (configuration space) $\pi(q^i, t) \rightarrow t$

$$\eta = \pi^*(dt) \in \Omega^1(Q) \qquad \eta = dt$$

- phase space of momenta

- extended T^*Q

- restricted $V^*\pi$ $V\pi = \{v \in TQ/\eta(v) = 1\}$

$$\Downarrow$$

$$\text{Principal } \mathbb{R}\text{-bundle } \mu : T^*Q \rightarrow V^*\pi \qquad \mu(q^i, t, p_i, p_t) \rightarrow (q^i, p_i, t)$$

- $h : V^*\pi \rightarrow T^*Q$ Hamiltonian section of μ $h(q^i, p_i, t) \rightarrow (q^i, p_i, t, -H(q^i, p_i, t))$

$$F_h : T^*Q \rightarrow \mathbb{R} \qquad F_h(q^i, t, p_i, p_t) \rightarrow H(q^i, p_i, t) + p_t$$

$$\mu(\alpha - h\mu(\alpha)) = 0 \implies \alpha - h\mu(\alpha) = F_h(\alpha)\eta$$

$$R_h \in \mathfrak{X}(V^*\pi) \qquad R_h(F) \circ \mu = \{F \circ \mu, F_h\} \qquad R_h = \frac{\partial}{\partial t} + \frac{\partial H}{\partial p_i} \frac{\partial}{\partial q^i} - \frac{\partial H}{\partial q^i} \frac{\partial}{\partial p_i}$$

- $W : Q \rightarrow \mathbb{R}$ the characteristic function $W(q^i, t)$

$$Q = M \times \mathbb{R}$$

$$h : V^*p_i = T^*M \times \mathbb{R} \rightarrow T^*Q = T^*(M \times \mathbb{R}), \quad h(q^i, p_i, t) \rightarrow (q^i, t, p_i, -H(q^i, p_i, t))$$

$$H : V^*\pi : T^*M \times \mathbb{R} \rightarrow \mathbb{R}$$

Hamilton-Jacobi Theorem for time-dependent Mechanics

The following sentences are equivalent

- 1 For every curve $c : I \rightarrow Q$ such that

$$c'(t) = T\tau_Q^* \circ X_{H_t}(dW_t(c(t)))$$

↓

$dW \circ c : I \rightarrow T^*Q$ is an integral curve of X_H .

- 2 W satisfies **Hamilton-Jacobi equation**

$$H_t \circ dW_t + \frac{\partial W}{\partial t} = \text{constant}$$

TOOLS

$\tau_Q : TQ \longrightarrow Q$, $\rightsquigarrow \tau_D : D \rightarrow Q$ a vector bundle with a almost linear Poisson bracket $\{\cdot, \cdot\}_{D^*}$

$\eta \in \Gamma(T^*Q)$ such that $d\eta = 0$ and $\eta(q) \neq 0 \quad \forall q \in Q \rightsquigarrow$ a section $\phi : Q \rightarrow D^*$ not null in everywhere such that $d^D\phi = 0$

$$\Downarrow$$

$\hat{\eta} : TQ \rightarrow \mathbb{R}$ linear function $\rightsquigarrow \hat{\phi} : D \rightarrow \mathbb{R}$ linear function

$\hat{\eta}^{-1}(0) = V\pi \quad \mu : T^*Q \rightarrow (\hat{\eta}^{-1}(0))^* \rightsquigarrow \hat{\phi}^{-1}(0) = V \quad \mu : D^* \rightarrow V^*$

$\{\cdot, \cdot\}_V^*$ linear almost Poisson bracket such that μ an almost Poisson morphism

A hamiltonian section $h : (\hat{\phi}^{-1}(0))^* \longrightarrow T^*Q \rightsquigarrow$ A section $h : V^* \rightarrow D^*$ of μ

$$F_h : D^* \rightarrow \mathbb{R}$$

A section $\lambda : Q \longrightarrow T^*Q$ such that $d\lambda = 0 \rightsquigarrow$ A section $\lambda : Q \rightarrow D^*$ of D^*

$$\Upsilon^\lambda : \Omega^1(D^*) \rightarrow \Gamma(D), \quad \delta_H^\lambda = \Upsilon^\lambda(dF_h) \in \Gamma(D)$$

Hamilton-Jacobi Theorem

$c : I \rightarrow Q$ integral curve of $R_h^\lambda = T\tau_{V^*} \circ R_h \circ \mu \circ \lambda \in \mathfrak{X}(Q)$

$\Rightarrow \mu \circ \lambda \circ c$ integral curve of $R_h \in \mathfrak{X}(V^*)$

\Downarrow

$$\mu \circ i_{\delta_h^\lambda} d^D \lambda + d^V(F_h \circ \lambda) = 0$$

HAMILTON-JACOBI EQUATION FOR MECHANICAL SYSTEMS WITH LINEAR EXTERNAL FORCES

- **The vector bundle:** $TQ \times \mathbb{R} \rightarrow Q$

- **The linear almost Poisson bracket:**

$\mathcal{F} : TQ \rightarrow TQ$ vector bundle morphism $\equiv \beta \in \Omega^1(TQ)$ semibasic homogeneous of degree 1

$$\Pi_{T^*Q \times \mathbb{R}} = \Pi_{T^*Q} + \frac{\partial}{\partial t} \wedge Y_{\mathcal{F}}$$

$$Y_{\mathcal{F}} \in \mathfrak{X}(T^*Q) \quad Y_{\mathcal{F}}(\alpha) = \mathcal{F}^*(\alpha)^\vee_\alpha \in T_\alpha(T^*Q)$$

- $R_h = X_H - Y_{\mathcal{F}} \in \mathfrak{X}(T^*Q)$
- **The 1-cocycle** $\phi = (0, 1) \in \Gamma(T^*Q \times \mathbb{R}) \cong C^\infty(Q) \times \mathfrak{X}(Q) \Rightarrow V = TQ$
- $\mu = p_1 : T^*Q \times \mathbb{R} \rightarrow T^*Q$
- **The Hamiltonian section:**
 $H : T^*Q \rightarrow \mathbb{R} \Rightarrow h : T^*Q \rightarrow T^*Q \times \mathbb{R}, \quad h(\beta) = (\beta, -H(\beta))$

HAMILTON-JACOBI EQUATION FOR MECHANICAL SYSTEMS WITH LINEAR EXTERNAL FORCES

$$\tau^\lambda : \Omega^1(T^*Q) \rightarrow \mathfrak{X}(Q), \quad \delta_H^\lambda = \tau(dH)$$

Hamilton-Jacobi Theorem

$$\lambda \in \Omega^1(Q)$$

$$c : I \rightarrow Q \text{ integral curve of } R_h^\lambda = T_{T^*Q} \circ X_H \circ \lambda \in \mathfrak{X}(Q)$$

$$\Rightarrow \lambda \circ c \text{ integral curve of } X_H - Y_{\mathcal{F}} \in \mathfrak{X}(T^*Q)$$



$$i_{\delta_H^\lambda} d\lambda + d(H \circ \lambda) + Y_{\mathcal{F}}(\lambda) = 0$$

THE HAMILTON-JACOBI EQUATION OF A MECHANICAL SYSTEM SUBJECTED TO AFFINE NONHOLONOMIC CONSTRAINTS

INGREDIENTS

- a vector subbundle $\tau : U \rightarrow Q$ of $(\tau_D : D \rightarrow Q, \{\cdot, \cdot\}_{D^*})$
- a bundle metric $\mathcal{G} : D \times_Q D \rightarrow \mathbb{R} \Rightarrow P : D = U \oplus U^\perp \rightarrow U$
- a function $V : Q \rightarrow \mathbb{R}$
- $X_0 \in \Gamma(D)$ such that $P(X_0) = 0$

↓

affine nonholonomic constraints $\equiv \tau_{\mathcal{U}} : \mathcal{U} \rightarrow Q$

$$q \in Q \longrightarrow \mathcal{U}_q = \{u_q + X_0(q)/u_q \in U_q\}$$

THE HAMILTON-JACOBI EQUATION OF A MECHANICAL SYSTEM SUBJECTED TO AFFINE NONHOLONOMIC CONSTRAINTS

- The vector bundle $\tau_{\tilde{U}} : \tilde{U} = (U^+)^* \rightarrow Q$ (it is a subbundle of $D \times \mathbb{R} \rightarrow Q$)

$$\Gamma(\tilde{U}) \equiv \langle \{(\sigma + fX_0, f) / \sigma \in \Gamma(U), f \in C^\infty(Q)\} \rangle$$

- The linear almost Poisson manifold on $\tilde{U}^* \cong U^+$



$([\![\cdot, \cdot]\!]_D, \rho_D)$ skewsymmetric algebroid

$$\tilde{P} : D \times \mathbb{R} \rightarrow \tilde{U}, \quad \tilde{P}(e_q, s) = (P(e_q) + sX_0(q), s)$$

$$P : D = U \oplus U^\perp \rightarrow U$$

$$[\![\sigma_1 + f_1X_0, f_1], [\sigma_2 + f_2X_0, f_2]\!]_{\tilde{U}} = \tilde{P}([\![\sigma_1 + f_1X_0, \sigma_2 + f_2X_0]\!]_D, \rho_D(\sigma_1 + f_1X_0)(f_2) - \rho_D(\sigma_2 + f_2X_0)(f_1))$$

$$\rho_{\tilde{U}}(\sigma + fX_0, f) = \rho_D(\sigma + fX_0)$$

- The 1-cocycle $\phi \in \Gamma(\tilde{U}^*)$

$$\phi : \Gamma(\tilde{U}) \rightarrow C^\infty(Q) \quad \phi(\sigma + fX_0, f) = f$$

THE HAMILTON-JACOBI EQUATION OF A MECHANICAL SYSTEM SUBJECTED TO AFFINE NONHOLONOMIC CONSTRAINTS

$$V = U, \quad (\llbracket \cdot, \cdot \rrbracket_U = P \circ \llbracket \cdot, \cdot \rrbracket_D, \quad \rho_U = \rho)$$

the Hamiltonian section $h : U^* \rightarrow \tilde{U}^*$

$$H : U^* \rightarrow \mathbb{R} \quad H(\alpha) = \frac{1}{2} \mathcal{G}_{U^*}(\alpha, \alpha) + V(q)$$

$$h(\gamma) = (u_q + sX_0(q), s) = \gamma_q(u_q) - sH(\gamma)$$

$$\Upsilon^\lambda : \Omega^1(U^*) \rightarrow \Gamma(U) \quad \delta_H^\lambda = \Upsilon^\lambda(dH) \in \Gamma(U)$$

Hamilton-Jacobi Theorem

Assume that $\lambda \in \Gamma(U^*)$

$c : I \rightarrow Q$ integral curve of $R_h^\lambda = T\tau_{U^*} \circ R_h \circ \lambda \in \mathfrak{X}(Q)$

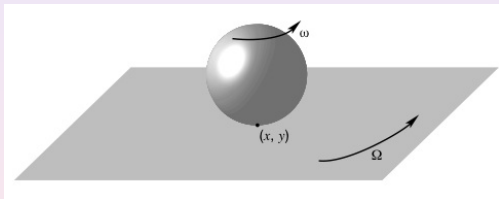
$\Rightarrow \lambda \circ c$ is a solution of Hamilton equations



$$i_{\delta_H^\lambda} d^U \lambda + \mu \circ i_{(X_0, 1)} d^{\tilde{U}}(h \circ \alpha) = 0$$

AN EXAMPLE: AN HOMOGENEOUS ROLLING BALL WITHOUT SLIDING ON A ROTATING TABLE WITH TIME-DEPENDENT ANGULAR VELOCITY

We consider a homogeneous ball with radius $r > 0$, mass m and inertia mk^2 about any axis. Suppose that the ball rolls without sliding on a horizontal table which rotates with a time-dependent angular velocity $\Omega(t)$ about vertical axis thought of one of its point. Apart from the gravitational force, no other external forces are assumed.



Configuration space: Choose a cartesian reference frame with origin at the center of rotation of the table and z -axis along the rotation axis. (q_1, q_2) = the position of the point of contact of the sphere with the table.

$$(t, q_1, q_2) \in Q := \mathbb{R}^3$$

AN EXAMPLE: AN HOMOGENEOUS ROLLING BALL WITHOUT SLIDING ON A ROTATING TABLE WITH TIME-DEPENDENT ANGULAR VELOCITY

$$(t, q^1, q^2, \dot{q}^1, \dot{q}^2, \omega_1, \omega_2, \omega_3) \in \mathbb{R} \times T\mathbb{R}^2 \times \mathbb{R}^3$$

ω_1, ω_2 and ω_3 are the components of the angular velocity of the sphere

- The extended phase space of momenta: $T^*\mathbb{R}^3 \times \mathbb{R}^3$
- The restricted phase space of momenta: $\mathbb{R} \times T^*\mathbb{R}^2 \times \mathbb{R}^3$

$$\mu : T^*\mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R} \times T^*\mathbb{R}^2 \times \mathbb{R}^3$$

The hamiltonian section $h : \mathbb{R} \times T^*\mathbb{R}^2 \times \mathbb{R}^3 \rightarrow T^*\mathbb{R}^3 \times \mathbb{R}^3$

$$h(t, q^i, p_i, \pi_i) = (t, q^i, -H(t, q^i, p_i, \pi_i), p_i, \pi_i)$$

$$H = \frac{1}{2} \left(\frac{1}{m}(p_1^2 + p_2^2) + \frac{1}{mk^2}(\pi_1^2 + \pi_2^2 + p_2^2) \right)$$

AN EXAMPLE: AN HOMOGENEOUS ROLLING BALL WITHOUT SLIDING ON A ROTATING TABLE WITH TIME-DEPENDENT ANGULAR VELOCITY

Ball without sliding



The affine constraints

$$\dot{q}_1 - r\omega_2 = -\Omega(t)q_2$$

$$\dot{q}_2 + r\omega_1 = \Omega(t)q_1$$

$$\Omega(t)q^2 + \frac{1}{m}p_1 - \frac{r}{mk^2}\pi_2 = 0$$

$$-\Omega(t)q^1 + \frac{1}{m}p_2 - \frac{r}{mk^2}\pi_1 = 0$$

AN EXAMPLE: AN HOMOGENEOUS ROLLING BALL WITHOUT SLIDING ON A ROTATING TABLE WITH TIME-DEPENDENT ANGULAR VELOCITY

Hamilton equations

$$\dot{q}^1 = \frac{1}{m} p_1$$

$$\dot{q}^2 = \frac{1}{m} p_2$$

$$\dot{p}_1 = -\frac{mk^2}{k^2 + r^2} \left(\frac{d\Omega(t)}{dt} q^2 + \Omega(t) \frac{p_2}{m} \right)$$

$$\dot{p}_2 = \frac{mk^2}{k^2 + r^2} \left(\frac{d\Omega(t)}{dt} q^1 + \Omega(t) \frac{p_1}{m} \right)$$

$$\dot{\pi}_1 = \frac{rmk^2}{k^2 + r^2} \left(\frac{d\Omega(t)}{dt} q^1 + \Omega(t) \frac{p_1}{m} \right)$$

$$\dot{\pi}_2 = \frac{rmk^2}{k^2 + r^2} \left(\frac{d\Omega(t)}{dt} q^2 + \Omega(t) \frac{p_2}{m} \right)$$

$$\dot{p}_3 = 0$$

AN EXAMPLE: AN HOMOGENEOUS ROLLING BALL WITHOUT SLIDING ON A ROTATING TABLE WITH TIME-DEPENDENT ANGULAR VELOCITY

The vector bundle: $\tau : D = T\mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}^3$

Global basis of $\Gamma(T\mathbb{R}^3 \times \mathbb{R}^3)$

$$\begin{aligned} e_0 &= \left(\frac{\partial}{\partial t} - \Omega(t)q^2 \frac{\partial}{\partial q^1} + \Omega(t)q^1 \frac{\partial}{\partial q^2}, 0 \right), & e_1 &= \left(\frac{\partial}{\partial q^1}, 0 \right), & e_2 &= \left(\frac{\partial}{\partial q^2}, 0 \right), \\ e_3 &= (0, (1, 0, 0)), & e_4 &= (0, (0, 1, 0)), & e_5 &= (0, (0, 0, 1)), \end{aligned}$$

The linear almost Poisson structure on $D^* = T^*\mathbb{R}^3 \times \mathbb{R}^3$

$$[[e_0, e_1]]_D = -\Omega(t)e_2, \quad [[e_0, e_2]]_D = \Omega(t)e_1, \quad [[e_3, e_4]]_D = e_5,$$

$$[[e_4, e_5]]_D = e_3, \quad [[e_5, e_3]]_D = e_4,$$

$$\rho_D(e_0) = \frac{\partial}{\partial t} - \Omega(t)q^2 \frac{\partial}{\partial q^1} + \Omega(t)q^1 \frac{\partial}{\partial q^2}, \quad \rho_D(e_1) = \frac{\partial}{\partial q^1}, \quad \rho_D(e_2) = \frac{\partial}{\partial q^2}.$$

AN EXAMPLE: AN HOMOGENEOUS ROLLING BALL WITHOUT SLIDING ON A ROTATING TABLE WITH TIME-DEPENDENT ANGULAR VELOCITY

Subbundle of D

$$U := \text{span}\{e_3 - re_2, e_4 + re_1, e_5\}$$

Fiber metric on D

$$\mathcal{G} = e_0^2 + (m((e_1)^2 + (e_2)^2) + mk^2((e_3)^2 + (e_4)^2 + (e_5)^2))$$

The section X_0 of D

$$X_0 = e_0$$

The section λ of U^*

$$\lambda = d^U(\varphi_1(t)q^1 + \varphi_2(t)q^2)$$

$$d^U\lambda \neq 0$$

AN EXAMPLE: AN HOMOGENEOUS ROLLING BALL WITHOUT SLIDING ON A ROTATING TABLE WITH TIME-DEPENDENT ANGULAR VELOCITY

If $\Omega(t) = \Omega_0 t$

Solution of Hamilton equations

$$\lambda \circ c(t) = (t, q^1(t), q^2(t); \lambda_3(c(t)), \lambda_4(c(t)), 0)$$

$$\lambda_3(c(t)) = \frac{-r}{\sqrt{m(k^2 + r^2)}} \left(C_1 \sin \left(\frac{r^2 \Omega_0 t^2}{2(k^2 + r^2)} \right) + C_2 \cos \left(\frac{r^2 \Omega_0 t^2}{2(k^2 + r^2)} \right) \right),$$

$$\lambda_4(c(t)) = \frac{r}{\sqrt{m(k^2 + r^2)}} \left(C_1 \cos \left(\frac{r^2 \Omega_0 t^2}{2(k^2 + r^2)} \right) - C_2 \sin \left(\frac{r^2 \Omega_0 t^2}{2(k^2 + r^2)} \right) \right),$$

where C_1, C_2 are real constants.

Using the linear almost Poisson theory (or skew-symmetric algebroid theory) we have given a simple method to describe the Hamilton-Jacobi equations for several situations. Usually, these equations make it easy to find solutions for the equations of Hamilton equations.

Thanks for your attention!